Automata on Finite Trees

Preliminaries

Trees

A *tree* over Σ is a partial function $t : \mathbb{N}^* \to \Sigma$ such that dom(t) is a prefix-closed set:

• for each $p \in dom(t)$ for all $q \leq p$ we have $q \in dom(t)$.

A word $p \in dom(t)$ is called a *position*.

If $p, q \in dom(t)$ such that $p \cdot n = q$ for some $n \in \mathbb{N}$:

- p is the *parent* of q,
- q is the *n*-th child of p.

Trees

Given a finite tree $t \in \mathcal{T}(\Sigma)$, the *frontier* of t is the set

$$fr(t) = \{ p \in dom(t) \mid \text{for all } n \in \mathbb{N} \ pn \notin dom(t) \}$$

A *path* in t is a **maximal subset** π of dom(t) linearly ordered by \leq .

Given $p \in dom(t)$, the *subtree* t_p is defined as

 $t_p: \{q \in \mathbb{N}^* \mid pq \in dom(t)\} \to \Sigma$

such that $t_p(q) = t(pq)$, for all $q \in dom(t_p)$.

Lemma 1 (König) A finitely branching tree is infinite if and only if it has an infinite path.

Coding ω -branching trees as binary trees

Let $t: \mathbb{N}^* \to \Sigma$ be a tree of arbitrary (possibly infinite) branching.

Define $t': \{0,1\}^* \to \Sigma \cup \{\bullet\}$ as follows:

- for all $n_1 n_2 \dots n_k \in dom(t)$, let $t'(1^{n_1} 0 1^{n_2} \dots 0 1^{n_k}) = t(n_1 n_2 \dots n_k)$,
- for all other p let $t'(p) = \bullet$

Tree Concatenation

Let $\sigma \in \Sigma$ and $T, T' \subseteq \mathcal{T}(\Sigma)$.

By $T \cdot_{\sigma} T'$ we denote the set of trees obtained from some $t \in T$ by replacing each occurrence of σ on fr(t) by a tree in T'.

If $\vec{\sigma} = \langle \sigma_1, \ldots, \sigma_n \rangle$, let $T \cdot_{\vec{\sigma}} \langle T_1, \ldots, T_m \rangle$ be the set of trees obtained from some $t \in T$ by replacing each occurrence of σ_i on fr(t) by a tree in T_i .

We denote by $T \cdot_{\vec{\sigma}} \langle T_1, \ldots, T_m \rangle^{\omega \vec{\sigma}}$ the set of infinite trees obtained by the infinite unfolding of the concatenation operation.

Terms

A ranked alphabet $\langle \Sigma, \# \rangle$ is a set of symbols together with a function $\# : \Sigma \to \mathbb{N}$. For $f \in \Sigma$, the value #(f) is said to be the *arity* of f.

Zero-arity symbols are called *constants*, and denoted by a, b, c, \ldots

A *term* t over Σ is a partial function $t : \mathbb{N}^* \to \Sigma$:

- dom(t) is a finite prefix-closed subset of \mathbb{N}^* , and
- for each $p \in dom(t)$, if #(t(p)) = n > 0 then $\{i \mid pi \in dom(t)\} = \{1, \dots, n\}.$

Contexts

Let $X = \{x_1, \ldots, x_n\}$ be a finite set of variables, interpreted over terms.

A term $t \in \mathcal{T}(\Sigma \cup X)$ is said to be *linear* if each variable occurs in t at most once.

A *context* is a linear term $C[x_1, \ldots, x_n]$, and $C[t_1, \ldots, t_n]$ denotes the result of replacing x_i with the term t_i , for all $1 \le i \le n$.

A context is said to be *trivial* if it is reduced to a variable, and *non-trivial* otherwise.

Bottom Up Tree Automata

Definition

Let $\Sigma = \{f, g, h, ...\}$ be a finite *ranked alphabet*. A *bottom-up tree automaton* is a tuple $A = \langle S, T, F \rangle$ where:

- S is a finite set of *states*,
- T is a set of *transition rules* of the form:

$$f(q_1,\ldots,q_n) \to q$$

where $f \in \Sigma$, #(f) = n, and $q_1, \ldots, q_n, q \in S$.

• $F \subseteq S$ is a set of final states.

Notice that there are no initial states.

If #(f) = 0 we have rules of the form $f \to q$.

Examples

1. Let $\Sigma = \{f, g, a\}$, where #(f) = 2, #(g) = 1 and #(a) = 0. Let $A = \langle S, T, F \rangle$, where:

- $S = \{q_f, q_g, q_a\},$
- $F = \{q_f\},$

•
$$T = \{a \to q_a, g(q_a) \to q_g, g(q_g) \to q_g, f(q_g, q_g) \to q_f\}$$

2. Let $\Sigma = \{red, black, nil\}$ with #(red) = #(black) = 2 and #(nil) = 0. Let $A_{rb} = \langle \{q_b, q_r\}, T, \{q_b\} \rangle$ with

$$T = \{nil \to q_b, black(q_{b/r}, q_{b/r}) \to q_b, red(q_b, q_b) \to q_r\}$$

Runs

A *run* of A over a tree $t : \mathbb{N}^* \to \Sigma$ is a mapping $\pi : dom(t) \to S$ such that, for each position $p \in dom(t)$, where $q = \pi(p)$:

• if #(t(p)) = n and $q_i = \pi(pi), 1 \le i \le n$, then T has a rule

 $t(p)(q_1,\ldots,q_n) \to q$

A run π is said to be *accepting*, if and only if $\pi(\lambda) \in F$.

The *language* of A, denoted as $\mathcal{L}(A)$ is the set of all trees over which A has an accepting run.

A set of trees $L \subseteq \mathcal{T}(\Sigma)$ is said to be a *rational tree language* iff there exists a bottom-up tree automaton A such that $\mathcal{L}(A) = L$.

A tree automaton is said to be *deterministic* iff there are no two transition rules with the same left-hand side.

Proposition 1 A deterministic tree automaton has at most one run for each input tree.

A tree automaton is said to be *complete* iff there exists at least one transition rule $f(q_1, \ldots, q_n) \to q$, for each $f \in \Sigma$, #(f) = n and $q_1, \ldots, q_n \in S$.

Proposition 2 A complete tree automaton has at least one run for each input tree.

Theorem 1 Let L be a rational tree language. Then there exists a complete deterministic tree automaton A such that $\mathcal{L}(A) = L$.

We define $A_d = \langle S_d, T_d, F_d \rangle$ where $S_d = 2^S$, $F_d = \{s \subseteq S \mid s \cap F \neq \emptyset\}$ and:

$$f(s_1, \dots, s_n) \to s \quad \Longleftrightarrow \quad s = \{q \in S \mid \exists q_1 \in s_1, \dots \exists q_n \in s_n : f(q_1, \dots, q_n) \to q\}$$
$$a \to s \quad \Longleftrightarrow \quad s = \{q \in S \mid a \to q\}$$

To prove $\mathcal{L}(A_d) = \mathcal{L}(A)$, we prove:

$$t \xrightarrow{*}_{A_d} s \iff s = \{q \in S \mid t \xrightarrow{*}_{A} q\}$$

By induction on the structure of t.

If t = a, by definition we have $a \to s \iff s = \{q \in S \mid a \to q\}$

If
$$t = f(t_1, \dots, t_n)$$
, by ind. hyp. $t_i \xrightarrow{*}_{A_d} s_i \iff s_i = \{q \in S \mid t_i \xrightarrow{*}_A q\}$

"
$$\Rightarrow$$
" if $t \xrightarrow{*}_{A_d} f(s_1, \dots, s_n) \xrightarrow{}_{A_d} s$ we show :
 $\exists q_i \in s_i \ . \ f(q_1, \dots, q_n) \xrightarrow{}_A q \iff t \xrightarrow{*}_A q$

"\(\leftarrow ") Let
$$s_i = \{q \mid t_i \xrightarrow{A} q\}, i = 1, \dots, n \text{ and}$$
$$s' = \{q \mid \exists q_i \in s_i \ . \ f(q_1, \dots, q_n) \xrightarrow{A} q\}$$

We conclude by showing $s = s' \square$

Closure Properties

Theorem 2 The class of rational tree languages is closed under union, complementation and intersection.

Union Let $A_i = \langle S_i, T_i, F_i \rangle$ for i = 1, 2. Suppose that $S_1 \cap S_2 = \emptyset$. Let $A_{\cup} = \langle S_1 \cup S_2, T_1 \cup T_2, F_1 \cup F_2 \rangle$.

Complementation Let $A = \langle S, T, F \rangle$ be a complete deterministic tree automaton such that $\mathcal{L}(A) = L$. Define $\overline{A} = \langle S, T, S \setminus F \rangle$.

Intersection We use the fact that $L_1 \cap L_2 = \overline{\overline{L_1} \cup \overline{L_2}}$.

Projection

Let $\Sigma = \Sigma_1 \times \Sigma_2 = \{(\sigma_1, \sigma_2) \mid \sigma_1 \in \Sigma_1, \sigma_2 \in \Sigma_2, \#(\sigma_1) = \#(\sigma_2)\}$

We define $pr_1(t) : \mathbb{N}^* \to \Sigma_1$, where $pr_1(t)(p) = \sigma_1$ iff there exist $\sigma_2 \in \Sigma_2$ such that $t(p) = \langle \sigma_1, \sigma_2 \rangle$.

 $pr_2(t)$ is defined in a similar way.

Theorem 3 If $L \subseteq \mathcal{T}(\Sigma_1 \times \Sigma_2)$ is a rational tree language, then so are the projections $pr_1(L)$ and $pr_2(L)$.

Minimization

A relation $\equiv \subseteq \mathcal{T}(\Sigma) \times \mathcal{T}(\Sigma)$ is a *congruence* on $\mathcal{T}(\Sigma)$ iff for every context $C[x_1, \ldots x_n]$:

$$\forall 1 \leq i \leq n \, . \, u_i \equiv v_i \Rightarrow C[u_1, \dots, u_n] \equiv C[v_1, \dots, v_n]$$

For a given tree language L, we define \equiv_L :

 $u \equiv_L v$ iff for all contexts C[x] we have $C[u] \in L \iff C[v] \in L$

Exercise 1 Show that \equiv_L is a congruence. \Box

A Myhill-Nerode Theorem for Tree Languages

Theorem 4 (Myhill-Nerode) A tree language is rational iff the congruence \equiv_L is of finite index.

" \Rightarrow " Let $A = \langle S, T, F \rangle$ be a *complete* TA such that $L = \mathcal{L}(A)$.

Let $u \equiv_A v$ iff $u \xrightarrow{*} q \iff v \xrightarrow{*} q$, for all $q \in S$. We have $u \equiv_A v \Rightarrow u \equiv_L v$.

"\Equiv " Define $A_{min} = \langle S_{min}, T_{min}, F_{min} \rangle$, where:

•
$$S_{min} = \{ [u]_L \mid u \in \mathcal{T}(\Sigma) \}$$

• $T_{min} = \{f([u_1]_L, \dots, [u_n]_L) = [f(u_1, \dots, u_n)]_L \mid u_1, \dots, u_n, u \in \mathcal{T}(\Sigma)\}$

•
$$F_{min} = \{ [u]_L \mid u \in L \}$$

Pumping Lemma for Rational Tree Languages

Lemma 2 (Pumping) Let L be a rational tree language. Then there exists a constant N > 0 such that, for every $t \in L$ with height(t) > N, there exists a context C, a non-trivial context D and a tree u such that $C[D[u]] \in L$, and, for all $n \ge 0$ we have $C[D^n[u]] \in L$.

Corollary 1 Let $A = \langle S, T, F \rangle$ be a tree automaton.

1. $\mathcal{L}(A) \neq \emptyset$ iff there exists $t \in \mathcal{L}(A)$ with height(t) < ||S||,

2. $\|\mathcal{L}(A)\| = \omega$ iff there exists $t \in \mathcal{L}(A)$ with $\|S\| < height(t) < 2\|S\|$.

Pumping Lemma for Rational Tree Languages

Exercise 2 Show that $\{f(g^n(a), g^n(a)) \mid n \ge 0\}$ is not rational. \Box

Exercise 3 (Homework) Let L be a rational tree language over the alphabet $\Sigma = \{f, a, b\}$, where #(f) = 2 and #(a) = #(b) = 0. Let $L^{ac} \supseteq L$ be the smallest tree language which is closed by the application of the two rules below:

• commutativity: for all context C and subtrees t_1, t_2 :

 $C[f(t_1, t_2)] \in L^{ac} \Rightarrow C[f(t_2, t_1)] \in L^{ac}$

• **associativity**: for all context C and subtrees t_1, t_2, t_3 :

 $C[f(f(t_1, t_2), t_3)] \in L^{ac} \Rightarrow C[f(t_1, f(t_2, t_3))] \in L^{ac}$

Show that there exists a rational tree language L for which L^{ac} is not rational. \Box

Decidability

- Emptiness $\mathcal{L}(A) = \emptyset$?
- Equality $\mathcal{L}(A) = \mathcal{L}(B)$?
- Infinity $\|\mathcal{L}(A)\| < \infty$?
- Universality $\mathcal{L}(A) = \mathcal{T}(\Sigma)$?

Theorem 5 The emptiness, equality, infinity and universality problems on tree automata are decidable. In particular, emptiness is decidable in time polynomial in the size (number of states) of automata.

Top Down Tree Automata

Definition

A top-down tree automaton is a tuple $A = \langle S, I, T, F \rangle$ where:

- S is a set of *states*,
- $I \subseteq S$ is a set of *initial states*,
- T is a set of *transition rules* of the form

$$q(f) \to \langle q_1, \ldots, q_n \rangle$$

where #(f) = n > 0.

• F is a set of *final states*

Notice that, for #(f) = 0 there are no rules in T.

Runs

A *run* of A over a tree $t : \mathbb{N}^* \to \Sigma$ is a mapping $\pi : dom(t) \to S$ such that, for each position $p \in dom(t)$, where $q = \pi(p)$, we have:

- if $p = \epsilon$ then $q \in I$, and
- if #(t(p)) = n and $q_i = \pi(pi), 1 \le i \le n$, then T has a rule

$$q(t(p)) \rightarrow \langle q_1, \ldots, q_n \rangle$$

A run π is said to be *accepting*, if and only if $\pi(p) \in F$, for all $p \in fr(t)$.

Theorem 6 Bottom up and top down tree automata recognize the same languages.

A top down tree automaton is said to be *deterministic* if it has one initial state and no two rules with the same left-hand side.

Proposition 3 A deterministic top down tree automaton has at most one run for each input tree.

Proposition 4 There exists a rational tree language that is not accepted by any top down deterministic tree automaton.

Proof: $L = \{f(a, b), f(b, a)\}$

Tree Automata and WSkS

MSOL on Trees: (W)S ω S

Let $\Sigma = \{a, b, \ldots\}$ be a tree alphabet. The alphabet of (W)S ω S is:

- the function symbols $\{s_i \mid i \in \mathbb{N}\}; s_i(x)$ denotes the *i*-th successor of x
- the set constants $\{p_a \mid a \in \Sigma\}$; p_a denotes the set of positions of a
- the first and second order variables and connectives.

From Automata to Formulae

Let $X_1, ..., X_k, x_{k+1}, ..., x_m$, and $\Sigma = \{0, 1\}^m \cup \{\bot\}.$

We work on binary trees w.l.o.g. $\#(\langle \sigma_0, \ldots, \sigma_m \rangle) = 2$ and $\#(\perp) = 0$.

Let $A = \langle S, I, T, F \rangle$ be a non-deterministic top-down tree automaton, where $S = \{s_1, \dots, s_p\}.$

Coding of Σ

Let
$$\sigma \in \{0,1\}^m \cup \{\bot\}$$
 and $\vec{X} = \langle X_1, \ldots, X_m, X_{m+1} \rangle$.

We define the formula $\Phi_{\sigma}(x, \vec{X})$ as the conjunction of:

- $X_i(x), 1 \le i \le m$, if $\sigma_i = 1$,
- $\neg X_i(x), 1 \le i \le m$, if $\sigma_i = 0$,
- $X_{m+1}(x)$, if $\sigma = \bot$.

It follows, that for any $t \in \mathcal{T}(\Sigma)$, we have $t \models \forall x \ . \ \bigvee_{\sigma \in \Sigma} \Phi_{\sigma}(x, \vec{X})$.

Coding of S

Let $\vec{Y} = \{Y_1, \dots, Y_p\}$ be set variables.

Intuitively, the set variable Y_i , $1 \le i \le p$ contains all tree positions labeled by A with state s_i during the run on some tree.

$$\Phi_S(\vec{Y}) : \forall z . \bigvee_{1 \le i \le p} Y_i(z) \land \bigwedge_{1 \le i < j \le p} \neg \exists z . Y_i(z) \land Y_j(z)$$

Coding of I, T and F

Every run starts from an initial state:

$$\Phi_I(\vec{Y}) : \exists x \forall y . x \le y \land \bigvee_{s_i \in I} Y_i(x)$$

If A is at position x and $t(x) \in \{0,1\}^m$, A moves on $\langle s_0(x), s_1(x) \rangle$:

$$\Phi_T(\vec{X}, \vec{Y}) : \bigwedge_{i=1}^p \forall x \, . \, Y_i(x) \land \bigvee_{\sigma \in \Sigma \setminus \{\bot\}} \Phi_\sigma(x, \vec{X}) \to \bigvee_{s_i(\sigma) \to \langle s_j, s_k \rangle} Y_j(s_0(x)) \land Y_k(s_1(x))$$

If A is at position x and $t(x) = \bot$, A must be in an accepting state:

$$\Phi_F(\vec{X}, \vec{Y}) : \forall x . \Phi_\perp(x, \vec{X}) \to \bigvee_{s_i \in F} Y_i(x)$$

From Formulae to Automata

Let φ : $x_2 \in X_1$.

We define $A_{\varphi} = \langle \{s_0, s_1\}, s_0, T, \{s_1\} \rangle$, where:

$$\begin{array}{rcl} \langle 0, 0 \rangle(s_0) & \to & \{ \langle s_0, s_1 \rangle, \langle s_1, s_0 \rangle \} \\ \langle 1, 0 \rangle(s_0) & \to & \{ \langle s_0, s_1 \rangle, \langle s_1, s_0 \rangle \} \\ \langle 1, 1 \rangle(s_0) & \to & \langle s_1, s_1 \rangle \\ \langle 0, 0 \rangle(s_1) & \to & \langle s_1, s_1 \rangle \\ \langle 1, 0 \rangle(s_1) & \to & \langle s_1, s_1 \rangle \\ & \bot(s_0) & \to & s_0 \\ & \bot(s_1) & \to & s_1 \end{array}$$

From Formulae to Automata

Let φ : $s_0(x_1) = x_2$.

We define $A_{\varphi} = \langle \{s_0, s_1, s_2\}, T, \{s_0\} \rangle$, where:

$$\begin{array}{rcccc} \langle 0,0\rangle & \to & s_2 \\ \langle 0,1\rangle & \to & s_1 \\ \langle 1,1\rangle & \to & s_0 \\ \langle 0,0\rangle(s_2,s_2) & \to & s_2 \\ \langle 0,1\rangle(s_2,s_2) & \to & s_2 \\ \langle 0,1\rangle(s_1,s_2) & \to & s_1 \\ \langle 1,0\rangle(s_1,s_2) & \to & s_0 \\ \langle 0,0\rangle(s_0,s_2) & \to & s_0 \\ \langle 0,0\rangle(s_2,s_0) & \to & s_0 \end{array}$$

From Formulae to Automata

As in the case of automata on words, A_{Φ} can be effectively constructed, for any formula Φ of WSkS.

Theorem 7 Given a ranked alphabet Σ , a tree language $L \subseteq \mathcal{T}(\Sigma)$ is definable in WSkS iff it is rational.

Corollary 2 The SAT problem for WSkS is decidable.