# Exact Global Optimization on Demand



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A *lazy* (CDCL-like) approach to *exact* nonlinear global optimization over the real numbers

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computable RCFs containing infinitesimals (de Moura - Passmore, 2013)

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• A practical application of nonstandard models!

### Exact Global Optimization



Many classes of optimization problems, based on restrictions of f's and b's

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Many classes of optimization problems, based on restrictions of f's and b's

nonlinear, computable

# What is a Real Closed Field?

# $\operatorname{RCF} = Th(\langle \mathbb{R}, +, *, <, 0, 1 \rangle)$

## What is a Real Closed Field?

### $RCF = Th(\langle \mathbb{R}, +, *, <, 0, 1 \rangle)$

Examples: The reals:  $\langle \mathbb{R}, +, *, <, 0, 1 \rangle$ 

• The algebraic reals:  $\langle \mathbb{R}_{alg}, +, *, <, 0, 1 \rangle$ • The (a!) Hyperreals:  $\left( \prod_{\mathbb{N}} \langle \mathbb{R}, +, *, <, 0, 1 \rangle \right) / \mathcal{U}$ 

• Real closures:  $\widetilde{\mathbb{K}}$  s.t.  $\mathbb{K} = \mathbb{Q}(t_1, \ldots, t_n, \epsilon_1, \ldots, \epsilon_m)$ 

# Optimization using RCF QE - I

#### RCF admits quantifier elimination (QE)

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In theory, one can exploit RCF QE to solve nonlinear optimization problems over the reals: *Let's see how! In the next slide...* 

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#### RCF admits quantifier elimination (QE)

In theory, one can exploit RCF QE to solve nonlinear optimization problems over the reals: *Let's see how! In the next slide...* 

In practice, this is not a viable solution: RCF QE is infeasible: O(2^2^(Omega(n)))

# Optimization using RCF QE - II



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$$\begin{array}{ll} \underset{\vec{x}}{\text{minimize}} & f(\vec{x}) \\ \text{subject to} & \bigwedge_{i=1}^{m} f_i(\vec{x}) \leq b_i \end{array}$$

Step 1: New coordinate function y

$$F(\vec{x}, y) \triangleq \left( y = f(\vec{x}) \land \bigwedge_{i=1}^{m} f_i(\vec{x}) \le b_i \right)$$

# Optimization using RCF QE - II



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m

#### Step 2: QE (project onto y)

Use RCF QE to eliminate  $\exists \vec{x} \text{ from } \exists \vec{x} F(\vec{x}, y)$ , obtaining  $\varphi(y)$  s.t.  $\varphi(y) \triangleq \bigvee_{i} \bigwedge_{j} (p_{i,j}(y) \bowtie_{i,j} 0), \qquad \bowtie_{i,j} \in \{<, \leq, =, \geq, >\}, \quad p_{i,j} \in \mathbb{Z}[y].$ 

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Step 3: Real Root Isolation (note sign invariance: IVT!)

Use univariate real root isolation (e.g., via Sturm sequences) to isolate all roots of  $p_{i,j}(y) \in \mathbb{Z}[y]$ . This partitions  $\mathbb{R}$  into 2k + 1 connected components.

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Sweep from L to R, looking for first connected component satisfying  $\varphi(y)$ 

### exact minimum found!

# Four Possible Outcomes

No satisfying region: Infeasible

 $\odot$  (-inf, r) : Unbounded

[r]: Exact minimum

∅ (r, \_): No minimum, but exact infimum

# Five Four Possible Outcomes

- No satisfying region: Infeasible
- [r] : Exact minimum
- ⌀ (r, \_) : No minimum, but exact infimum

#### Computing $\varphi(y)$ explicitly is a bad idea!

# A CAD-based Approach

- Used by Mathematica
- Doesn't require explicit computation of Phi(y)
- But, it is eager and pessimistic
- Our new approach is *lazy* and *optimistic*
- First, let's understand the CAD-based approach...

### Cylindrical Algebraic Decomposition

CAD: A partitioning of  $\mathbb{R}^n$ into finitely many RCF-definable connected components which "behaves nicely" w.r.t. projections onto lower dimensions.

$$P \subset \mathbb{Z}[x_1, \dots, x_n]$$
-invariant **CAD**  
**CAD of**  $\mathbb{R}^n$  s.t. for all cells  $c_i$ , all  $p \in P$   
 $\forall \vec{r} \in c_i(p(\vec{r}) = 0) \lor$   
 $\forall \vec{r} \in c_i(p(\vec{r}) > 0) \lor$   
 $\forall \vec{r} \in c_i(p(\vec{r}) < 0)$ .



CAD sphere diagrams: C. Brown and QEPCAD-B

P

0

# CAD Phase I: Projection

 $Proj_{i+1}: \mathbb{Z}[x_1, \ldots, x_{i+1}] \to \mathbb{Z}[x_1, \ldots, x_i]$ 

Inductive Property: A (P\_{i+1})-invariant CAD for R^{i+1} can be constructed from a (P\_i)-invariant CAD of R^i.

 $P_n = P \subset \mathbb{Z}[x_1, \dots, x_n]$  $P_{n-1} = Proj(P_n) \subset \mathbb{Z}[x_1, \dots, x_{n-1}]$ 

 $P_2 = Proj(P_3) \subset \mathbb{Z}[x_1, x_2]$  $P_1 = Proj(P_2) \subset \mathbb{Z}[x_1]$ 



CAD sphere diagrams: C. Brown and QEPCAD-B

# Projection sets $P_3 = \{x_1^2 + x_2^2 + x_3^2 - 4\}$ $P_2 = \{x_2^2 + x_1^2 - 4\}$ $P_1 = \{x_1 + 2, x_1 - 2\}$



#### Base Phase: R^1

### Projection sets

 $P_3 = \{x_1^2 + x_2^2 + x_3^2 - 4\}$  $P_2 = \{x_2^2 + x_1^2 - 4\}$  $P_1 = \{\bar{x_1} + 2, \bar{x_1} - 2\}$ 



Lifting Phase: R^1 -> R^2

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Lifting Phase: R^2 -> R^3

# A CAD-based Approach to Optimization



Step 1: New coordinate function y

 $F(\vec{x}, y) \triangleq \left( y = f(\vec{x}) \land \bigwedge_{i=1}^{m} f_i(\vec{x}) \le b_i \right)$ 

 $P_{n+1} = \{y - f(\vec{x}), f_1(\vec{x}) - b_1, \dots, f_m(\vec{x}) - b_m\} \subset \mathbb{Z}[y, x_1, \dots, x_n]$  $P_n = Proj(P_{n+1}) \subset \mathbb{Z}[y, x_1, \dots, x_{n-1}]$ 

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#### Step 3: CAD Base and Lifting (depth-first) from L to R



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#### Step 2: CAD projection (with y lowest variable)

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Step 3: CAD Base and Lifting (depth-first) from L to R



## Recap of CAD-based Approach

- Used by Mathematica
- Doesn't require explicit computation of Phi(y)
- But, it is *eager* and *pessimistic:* FULL CAD Projection (expensive!!!)
- Our new approach is *lazy* and *optimistic*
- We build on *nlsat/mcsat*, a CDCL-like approach to the Existential fragment of RCF

## nlsat/mcsat: CDCL-like approach to ExRCF

- Start building model for formula immediately, without first going through projection phase
- When conflict arises, use projection on demand
- Real-algebraic analogue of *conflict clauses* **generalize** a non-extendable partial models to rule out a *delineable* region containing them
- Non-chronological backtracking

\* Typically much more efficient on ExRCF SMT problems than classical (eager & pessimistic) CAD!

## nlsat: CDCL-like approach to ExRCF



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Key ideas: Use partial solution to guide the search  $x^3 + 2x^2 + 3y^2 - 5 < 0$ **Feasible Region** Ψ Starting search -4xy - 4x + y > 1-2Partial solution: 0.5 X What is the core? Can we extend it to y?  $x^2 + y^2 < 1$ 



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## CAD-based optimization + nlsat = ?

CAD-based Optimization uses projection eagerly and pessimistically

nlsat/mcsat solves Exists RCF by using projection lazily and optimistically

...but how can we combine the two?

- We use coordinate function y to represent the objective function
- Then, we need to *sweep* along all possible values of y from Left to Right
- After CAD projection, we can do this
- But, what about with nlsat/mcsat?



#### VS

### where to start? how to move to `next' region?

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Key idea: RCFs containing infinitesimals!

-1/epsilon

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-1/epsilon rr+epsilon

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Computing with Infinitesimals & Computable Transcendentals Technique explained in our 2013 CADE paper

> Computation in Real Closed Infinitesimal and Transcendental Extensions of the Rationals



## **Real Closed Fields**





## **Real Closed Fields**







## Our approach

Tower of extensions Hybrid representation Interval (arithmetic) + Thom's lemma Clean denominators Non-minimal defining polynomials

## Tower of extensions

Basic Idea:

Given (computable) ordered field KImplement  $K(\varsigma)$ 

## Tower of extensions

(Computable) ordered field *K* Operations: +, -, ×, *inv*, *sign* 

 $a < b \Leftrightarrow sign(a - b) = -1$ 

Binary Rational  $\frac{a}{2^k}$ 

Approximation:  $approx(a) \in B_{\infty}$ -interval  $B_{\infty} = B \cup \{-\infty, \infty\}$  $a \neq 0 \Rightarrow 0 \notin approx(a)$ 

#### Refine approximation

### (Computable) Transcendental Extensions

#### $approx(\pi)(k) \in B_{\infty}$ -interval

 $\forall n \in \mathbb{N}^+, \exists k \in \mathbb{N}, width(approx(\pi)(k)) < \frac{1}{n}$ 

Elements of the extension are encoded as rational functions

$$\frac{\pi^2 + \pi - 2}{\pi + 1}$$

### (Computable) Transcendental Extensions

$$\frac{1}{2}\pi + \frac{1}{\pi+1} = \frac{\frac{1}{2}\pi^2 + \frac{1}{2}\pi + 1}{\pi+1}$$

Standard normal form for rational functions GCD(numerator, denominator) = 1 Denominator is a monic polynomial

### (Computable) Transcendental Extensions

Refine interval Interval arithmetic Refine coefficients and extension

Zero iff numerator is the zero polynomial If q(x) is not the zero polynomial, then  $q(\pi)$  can't be zero, since  $\pi$  is transcendental.

Remark  $\sqrt{\pi}$  is transcendental with respect to  $\mathbb{Q}$ 

 $\sqrt{\pi}$  is not transcendental with respect to  $\mathbb{Q}(\pi)$ 

### Infinitesimal Extensions

Every infinitesimal extension is transcendental

**Rational functions** 

 $sign(a_0 + a_1\epsilon + ... + a_n\epsilon^n)$ sign of first non zero coefficient

$$approx(\epsilon) = (0, \frac{1}{2^k})$$

Non-refinable intervals  $approx\left(\frac{1}{\epsilon}\right) = (2^k, \infty)$ 

### **Algebraic Extensions**

 $K(\alpha)$  $\alpha$  is a root of a polynomial with coefficients in K

Encoding α as polynomial + interval does not work K may not be Archimedian Roots can be infinitely close to each other. Roots can be greater than any Real.

Thom's Lemma

We can always distinguish the roots of a polynomial in a RCF using the signs of the derivatives

### **Algebraic Extensions**

Roots:  $-\sqrt{1/\epsilon}, \sqrt{1/\epsilon}, \sqrt[3]{1/\epsilon}$ 

## Three roots of $\epsilon^2 x^5 - \epsilon x^3 - \epsilon x^2 + 1 \in (\mathbb{Q}(\epsilon))[x]$

$$\begin{array}{l} (\epsilon^2 x^5 - \epsilon x^3 - \epsilon x^2 + 1, (-\infty, 0), \{\}) \\ (\epsilon^2 x^5 - \epsilon x^3 - \epsilon x^2 + 1, (0, \infty), \quad \{60\epsilon^2 x^2 - 6\epsilon > 0\}) \\ (\epsilon^2 x^5 - \epsilon x^3 - \epsilon x^2 + 1, (0, \infty), \quad \{60\epsilon^2 x^2 - 6\epsilon < 0\}) \end{array}$$

### **Algebraic Extensions**

Given  $H = \{h_1, ..., h_n\}$ , signdet(H, p, a, b)Feasible sign assignments of H at roots of p in (a, b)Based on Sturm-Tarski Theorem Ben-Or et al algorithm.

 $sign(q(\alpha))$  where  $\alpha = (p, (a, b), S)$ R = signdet(poly(S), p, (a, b))

if  $S \cup \{q = 0\} \in R$  then  $q(\alpha) = 0$ , if  $S \cup \{q > 0\} \in R$  then  $q(\alpha) > 0$ , if  $S \cup \{q < 0\} \in R$  then  $q(\alpha) < 0$ . The procedure MkInfinitesimal creates a new infinitesimal extension, while Pi and E return  $\pi$  and e respectively. In the following example, we extract the first (and only) root of the polynomial  $x^3 + \epsilon x^2 + (\sqrt{2} + \pi) x - \pi$ .

1/epsilon

amounts of

fun! :-)

Compute with infinitesimals and transcendentals online!

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```
z3rc1
Explore the RCF package using Python
    1 # Create Pi, Euler's constants and an infinitesimal.
    2 pi = Pi()
    3 e = E()
    4 eps = MkInfinitesimal()
    6 print("Let r0 be the first root of x^4 + -2*eps*x^3 + (eps^2 + -4)*x^2 + 4*eps*x + -2*eps
    7 r0 = MkRoots([4 - 2*eps**2, 4*eps, (eps**2 - 4), -2*eps, 1])[0]
    8 print(r0)
    9 print("")
   10
   11 print("Let r1 be the first root of (-1*eps**6 + 8*eps**4 + -20*eps**2 + 16)*r0 + -8*eps**
   12 r1 = MkRoots([(-1*eps**6 + 8*eps**4 + -20*eps**2 + 16)*r0 + -8*eps**5 + 32*eps**3 + -32*e
   13 print(r1)
   14 print("")
   15
   16 print("Let r2 be the first root of x^5 + 3*x^3 + r1*x^2 - 1")
   17 r2 = MkRoots([-1, 0, r1, 3, 1])[0]
   18 print(r2)
   19 print("")
   21 print("Let r3 be the first root of x^5 + r1*x^3 + pi*r2*x^2 - 3")
   22 r3 = MkRoots([-3, 0, pi*r2, r1, 0, 1])[0]
              home permalink
             '⊨' shortcut: Alt+B
```

← → C ise4fun.com/Z3RCF/tower8

Research

### Back to optimization...

# Key difficulty: Sweeping L to R

- We use coordinate function y to represent the objective function
- Then, we need to *sweep* along all possible values of y from Left to Right
- After CAD projection, we can do this
- But, what about with nlsat?



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```
procedure Min(F(\vec{x}, y))
   G := true
   \epsilon := MkInfinitesimal() (* create an infinitesimal value *)
   loop
      r := \operatorname{Min}_0(G)
      case r of
         unsat \Rightarrow return unsat
         unbounded \Rightarrow v := -\frac{1}{\epsilon}
         (\inf, a) \Rightarrow v := a + \epsilon
         (\min, a) \Rightarrow v := a
      end
      case Check(F(\vec{x}, y), \{y \mapsto v\}) of
         sat \Rightarrow return r
         (unsat, S) \Rightarrow G := G \land S
      end
   end
```

Min\_0: Procedure for Univariate Optimization Problem
Check: Procedure for SAT Modulo Assignment Problem,
with support for RCFs containing *infinitesimals*,
and satisfying the *finite decomposition* property.

### The RCF Optimization Problem

**Input:** A quantifier-free RCF formula  $F(\vec{x}, y)$ .

**Output** (with 'is (un)sat' meaning 'is (un)satisfiable over  $\mathbb{R}$ '):

unsat,if  $F(\vec{x}, y)$  is unsat,unbounded,if for all v exists w < v s.t.  $F(\vec{x}, w)$  is sat,(inf, a),if for all  $v \leq a$ ,  $F(\vec{x}, a)$  is unsat, andfor all  $\epsilon > 0$  exists  $v \in (a, a + \epsilon)$  s.t.  $F(\vec{x}, v)$  is sat,(min, a),if  $F(\vec{x}, a)$  is sat, and for all v < a,  $F(\vec{x}, v)$  is unsat.

# Conclusion

 A CDCL-like approach to exact nonlinear global optimization over the real numbers (and all RCFs)

Three main conceptual ingredients:

**CAD-based approach to optimization** eager method for nonlinear optimization, in Mathematica v9.x

#### nlsat/mcsat - existential CAD `on demand'

lazy CDCL-like approach to Exists RCF, in Z3 (Jovanović - de Moura, 2012)

#### computable nonstandard RCFs

computable RCFs containing infinitesimals (de Moura - Passmore, 2013)

### Thank you!