

Infinite Games

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Motivation: Build Correct HW/SW Systems

- ▶ Use **logic** to specify correctness properties, e.g.:
 - ▶ *every job sent to the printer is eventually printed*
 - ▶ *two jobs do not overlap (only one job is printed at a time)*
 - ▶ *a job that is canceled will be interrupted*

These are conditions on infinite sequences (system runs), and can be specified by automata and logical formulas.

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- ▶ Given a **logical specification**, we can do either:
 - ▶ **VERIFICATION**: **prove** that a given system satisfies the specification
 - ▶ **SYNTHESIS**: **build** a system that satisfies the specification

Intuition of Infinite Games

Two players:

1. Printer controller is Player 0
2. Users are Player 1

A **play** of a game is an infinite sequence of states of printer transition system, where the two players choose moves alternatively.

Player 0 (printer controller) **wins** the play if all conditions are satisfied independent of the choices Player 1 (user) makes. This corresponds to finding a **winning strategy** for Player 0 in an infinite game.

Our Aim

Solution of the Synthesis Problem

1. Decide whether there exists such a winning strategy -
Realizability Problem
2. If “yes”, then construct the system - **Synthesis Problem**

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Main result:

The synthesis problem is algorithmically solvable for finite-state systems with respect to specifications given as ω -automata or linear-time temporal logic.

Other Applications of Games

- ▶ Program repair or program sketching
- ▶ Nicer and more intuitive proofs for logics over trees
- ▶ Verification for logics over trees

Outline

1. Terminology
2. Safety and Reachability games
3. Büchi and coBüchi games

Terminology

Terminology

Two-player games between Player 0 and 1

An **infinite game** $\langle G, \phi \rangle$ consists of

- ▶ a **game graph** G and
- ▶ a **winning condition** ϕ .

G defines the “playground”, in which the two players compete.

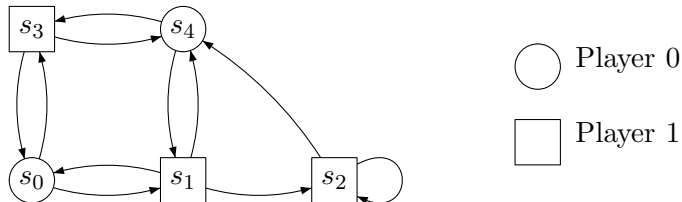
ϕ defines which plays are won by Player 0.

If a play does not satisfy ϕ , then Player 1 wins on this play.

Game Graphs

A **game graph** is a tuple $G = \langle S, S_0, T \rangle$ where:

- ▶ S is a finite set of **states**,
- ▶ $S_0 \subseteq S$ is the set of **Player-0 states** ($S_1 = S \setminus S_0$ are the **Player-1 states**),
- ▶ $T \subseteq S \times S$ is a **transition relation**. We assume that each state has at least one successor.



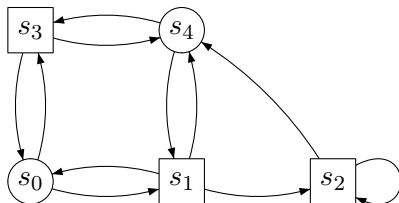
Plays

A **play** is an infinite sequence of states $\rho = s_0 s_1 s_2 \dots \in S^\omega$ such that for all $i \geq 0$ $\langle s_i, s_{i+1} \rangle \in T$.

It starts in s_0 and it is built up as follows:

If $s_i \in S_0$, then Player 0 chooses an edge starting in s_i , otherwise Player 1 picks such an edge.

Intuitively, a token is moved from state to state via edges: From S_0 -states Player 0 moves the token, from S_1 -states Player 1 moves the token.



Winning Condition

The winning condition describes the plays won by Player 0.

A **winning condition or winning objective** ϕ is a subset of plays, i.e., $\phi \subseteq S^\omega$.

We use logical conditions (e.g., LTL formulas) or automata theoretic acceptance conditions to describe ϕ .

Example:

- ▶ $\Box \Diamond s$ for some state $s \in S$
- ▶ All plays that stay within a **safe region** $F \subseteq S$ are in ϕ .
- ▶ Given a priority function $p : S \rightarrow \{0, 1, \dots, d\}$, all plays in which the smallest priority visited is even.

Games are named after their winning condition, e.g., Safety game, Reachability game, LTL game, Parity game,...

Types of Games

Given a play ρ , we define

- ▶ $\text{Occ}(\rho) = \{s \in S \mid \exists i \geq 0 : s_i = s\}$
- ▶ $\text{Inf}(\rho) = \{s \in S \mid \forall i \geq 0 \exists j > i : s_j = s\}$

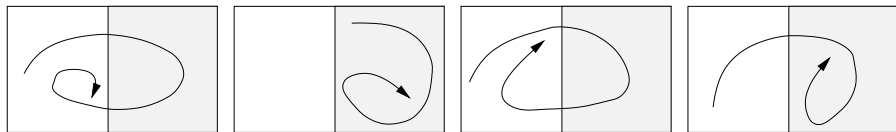
Given a set $F \subseteq S$,

Reachability Game $\phi = \{\rho \in S^\omega \mid \text{Occ}(\rho) \cap F \neq \emptyset\}$

Safety Game $\phi = \{\rho \in S^\omega \mid \text{Occ}(\rho) \subseteq F\}$

Büchi Game $\phi = \{\rho \in S^\omega \mid \text{Inf}(\rho) \cap F \neq \emptyset\}$

Co-Büchi Game $\phi = \{\rho \in S^\omega \mid \text{Inf}(\rho) \subseteq F\}$



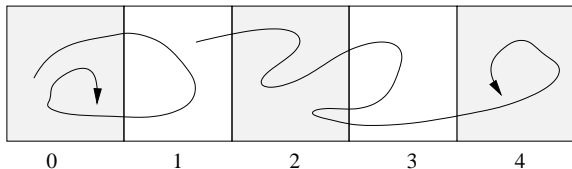
Types of Games

Given a priority function $p : S \rightarrow \{0, 1, \dots, d\}$ or an LTL formula φ

Weak-Parity Game $\phi = \{\rho \in S^\omega \mid \min_{s \in \text{Occ}(\rho)} p(s) \text{ is even}\}$

Parity Game $\phi = \{\rho \in S^\omega \mid \min_{s \in \text{Inf}(\rho)} p(s) \text{ is even}\}$

LTL Game $\phi = \{\rho \in S^\omega \mid \rho \models \varphi\}$



We will refer to the type of a game and give F , p , or φ instead of defining ϕ .

We will also talk about Muller and Rabin games.

Strategies

A **strategy** for Player 0 from state s is a function

$$f : S^*S_0 \rightarrow S$$

specifying for any sequence of states s_0, s_1, \dots, s_k with $s_0 = s$ and $s_k \in S_0$ a successor state s_j such that $(s_k, s_j) \in T$.

A play $\rho = s_0s_1\dots$ is **compatible** with strategy f if for all $s_i \in S_0$ we have that $s_{i+1} = f(s_0s_1\dots s_i)$.

(Definitions for Player 1 are analogous.)

Given strategies f and g from s for Player 0 and 1, respectively. We denote by $G_{f,g}$ the (unique) play that is compatible with f and g .

Winning Strategies and Regions

Given a game (G, ϕ) with $G = (S, S_0, E)$, a strategy f for Player 0 from s is called a **winning strategy** if for all Player-1 strategies g from s , if $G_{f,g} \in \phi$ holds. Analogously, a Player-1 strategy g is winning if for all Player-0 strategies f , $G_{f,g} \notin \phi$ holds.

Player 0 (resp. 1) wins from s if s/he has a winning strategy from s .

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Player 0 (resp. 1) wins from s if s/he has a winning strategy from s .

The **winning regions** of Player 0 and 1 are the sets

$$W_0 = \{s \in S \mid \text{Player 0 wins from } s\}$$

$$W_1 = \{s \in S \mid \text{Player 1 wins from } s\}$$

Note each state s belongs at most to W_0 or W_1 . Otherwise pick winning strategies f and g from s for Player 0 and 1, respectively, then $G_{f,g} \in \phi$ and $G_{f,g} \notin \phi$: Contradiction.

Questions About Games

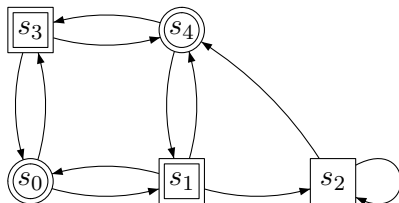
Solve a game (G, ϕ) with $G = (S, S_0, T)$:

1. Decide for each state $s \in S$ if $s \in W_0$.
2. If yes, construct a suitable winning strategy from s .

Further interesting question:

- ▶ Optimize construction of winning strategy (e.g., time complexity)
- ▶ Optimize parameters of winning strategy (e.g., size of memory)

Example



Safety game (G, F) with $F = \{s_0, s_1, s_3, s_4\}$, i.e., $\text{Occ}(\rho) \subseteq F$

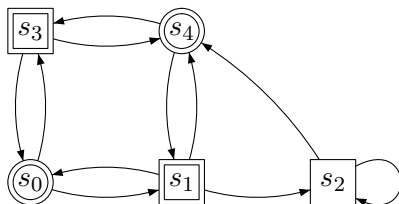
A winning strategy for Player 0 (from state s_0 , s_3 , and s_4):

- ▶ From s_0 choose s_3 and from s_4 choose s_3

A winning strategy for Player 1 (from state s_1 and s_2):

- ▶ From s_1 choose s_2 , from s_2 choose s_4 , and from s_3 choose s_4

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Safety game (G, F) with $F = \{s_0, s_1, s_3, s_4\}$, i.e., $\text{Occ}(\rho) \subseteq F$

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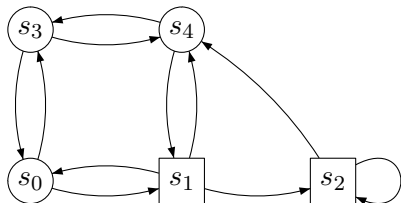
- ▶ From s_0 choose s_3 and from s_4 choose s_3

A winning strategy for Player 1 (from state s_1 and s_2):

- ▶ From s_1 choose s_2 , from s_2 choose s_4 , and from s_3 choose s_4

$W_0 = \{s_0, s_3, s_4\}$, $W_1 = \{s_1, s_2\}$

Another Example



LTL game (G, φ) with $\varphi = \diamond s_0 \wedge \diamond s_4$ (visit s_0 and s_4)

Winning strategy for Player 0 from s_0 :

- ▶ From s_0 to s_3 , from s_3 to s_4 , and from s_4 to s_1 .

Note: this strategy is not winning from s_3 or s_4 .

Winning strategy for Player 0 from s_3 :

- ▶ From s_0 to s_3 , from s_4 to s_3 , and from s_3 to s_0 on first visit, otherwise to s_4 .

Determinacy

Recall: the winning regions are disjoint, i.e., $W_0 \cap W_1 = \emptyset$

Question: Is every state winning for some player?

A game (G, ϕ) with $G = (S, S_0, E)$ is called **determined** if $W_0 \cup W_1 = S$ holds.

Remarks:

1. We will show that all automata theoretic games we consider here are determined.
2. There are games which are not determined (e.g., Tic-Tac-Toe)

Strategy Types

In general, a strategy is a function $f : S^+ \rightarrow S$.

1. **Computable or recursive strategies:** f is computable
2. **Finite-state strategies:** f is computable with a finite-state automaton meaning that f has bounded information about the past (history).
3. **Memoryless or positional strategies:** f only depends on the current state of the game (no knowledge about history of play)

Positional Strategies

Given a game (G, ϕ) with $G = (S, S_0, E)$, a strategy $f : S^+ \rightarrow S$ is called **positional or memoryless** if for all words $w, w' \in S^+$ with $w = s_0 \dots s_n$ and $w' = s'_0 \dots s'_m$ such that $s_n = s'_m$, $f(w) = f(w')$ holds.

A positional strategy for Player 0 is representable as

1. a function $f : S_0 \rightarrow S$
2. a set of edges containing for every Player-0 state s exactly one edge starting in s (and for every Player-1 state s' all edges starting in s')

Finite-state Strategies

A **strategy automaton** over a game graph $G = (S, S_0, E)$ is a finite-state automaton $A = (M, m_0, \delta, \lambda)$ with alphabet S , where

- ▶ M is a finite set of states (called **memory**),
- ▶ $m_0 \in M$ is an initial state (the initial **memory content**),
- ▶ $\delta : M \times S \rightarrow M$ is a transition function (the **memory update fct**),
- ▶ $\lambda : M \times S \rightarrow S$ is a labeling function (called the **choice function**).

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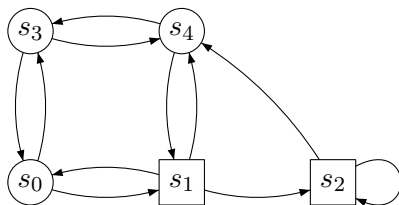
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The strategy for Player 0 computed by A is the function

$$f_A(s_0 \dots s_k) := \lambda(\delta(m_0, s_0 \dots s_{k-1}), s_k) \text{ with } s_k \in S_0$$

and the usual extension of δ to words: $\delta(m_0, \epsilon) = m_0$ and $\delta(m_0, s_0 \dots s_k) = \delta(\delta(m_0, s_0 \dots s_{k-1}), s_k)$. Any strategy f , such that there exists an A with $f_A = f$, is called **finite-state strategy**.

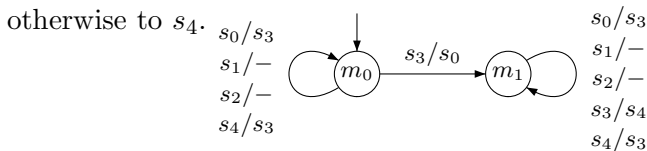
Recall Example



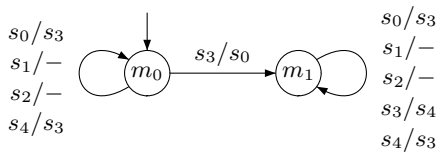
Objective: visit s_0 and s_4 , i.e. $\{s_0, s_4\} \subseteq \text{Occ}(\rho)$

Winning strategy for Player 0 from s_0 , s_3 and s_4 :

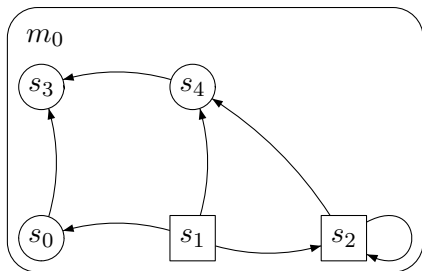
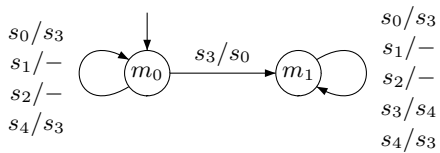
- From s_0 to s_3 , from s_4 to s_3 , and from s_3 to s_0 on first visit, otherwise to s_4 .



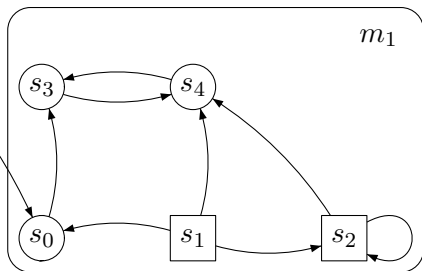
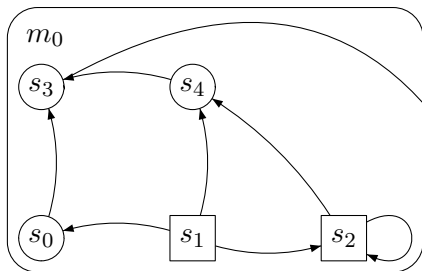
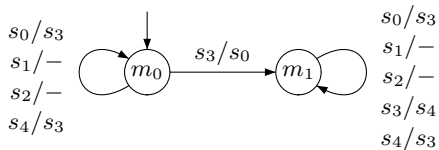
Extended Game



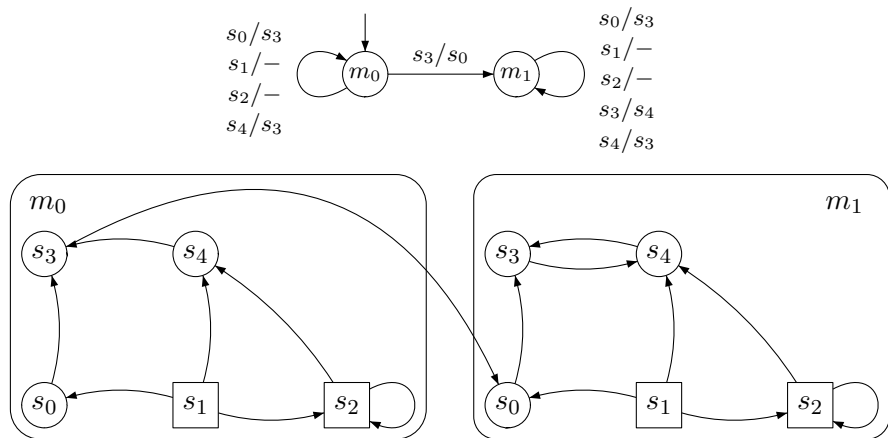
Extended Game



Extended Game



Extended Game



Note: the strategy in the extended game graph is memoryless.

Reachability and Safety Games

Reachability and Safety Games

Theorem

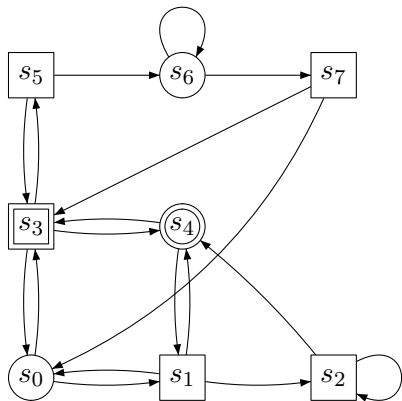
Given a reachability game (G, F) with $G = (S, S_0, E)$ and $F \subseteq S$, then the winning regions W_0 and W_1 of Player 0 and 1, respectively, are computable, and both players have corresponding memoryless winning strategies.

Proof.

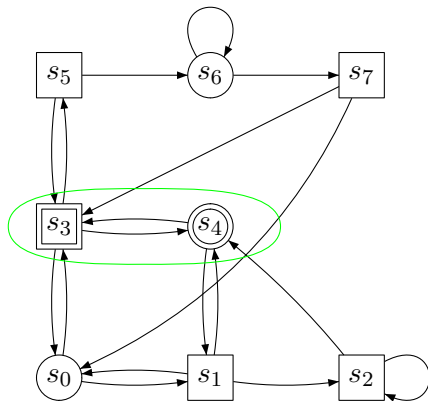
Define

$$\text{Attr}_0^i(F) := \{s \in S \mid \text{Player 0 can force a visit from } s \text{ to } F \\ \text{in less than } i \text{ moves}\}$$

Example

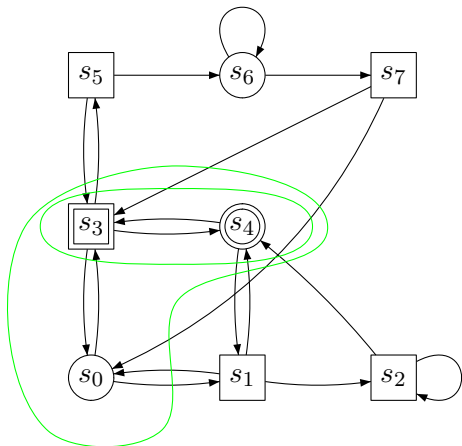


Example



$$\text{Attr}_0^0 = \{s_3, s_4\}$$

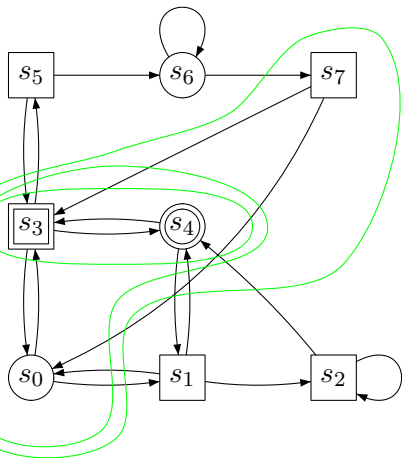
Example



$$\text{Attr}_0^0 = \{s_3, s_4\}$$

$$\text{Attr}_0^1 = \{s_0, s_3, s_4\}$$

Example

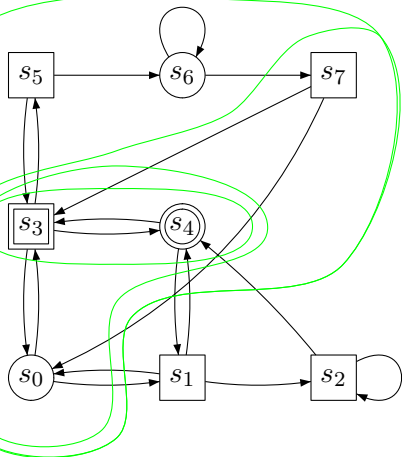


$$\text{Attr}_0^0 = \{s_3, s_4\}$$

$$\text{Attr}_0^1 = \{s_0, s_3, s_4\}$$

$$\text{Attr}_0^2 = \{s_0, s_3, s_4, s_7\}$$

Example



$$\text{Attr}_0^0 = \{s_3, s_4\}$$

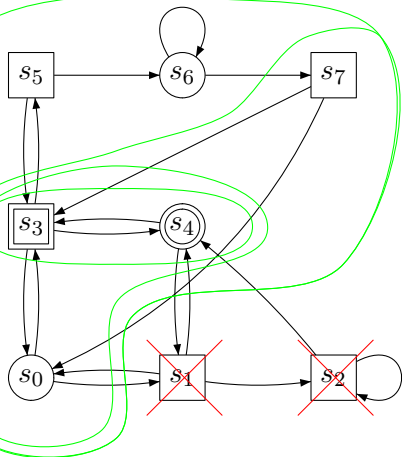
$$\text{Attr}_0^1 = \{s_0, s_3, s_4\}$$

$$\text{Attr}_0^2 = \{s_0, s_3, s_4, s_7\}$$

$$\text{Attr}_0^3 = \{s_0, s_3, s_4, s_6, s_7\}$$

$$\text{Attr}_0^4 = \{s_0, s_3, s_4, s_5, s_6, s_7\}$$

Example



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Computing the Attractor

Construction of $\text{Attr}_0^i(F)$:

$$\text{Attr}_0^0(F) = F$$

$$\text{Attr}_0^{i+1}(F) = \text{Attr}_0^i(F) \cup$$

$$\{s \in S_0 \mid \exists s' \in S : (s, s') \in E \wedge s' \in \text{Attr}_0^i(F)\} \cup$$

$$\{s \in S_1 \mid \forall s' \in S : (s, s') \in E \rightarrow s' \in \text{Attr}_0^i(F)\}$$

Then

$\text{Attr}_0^0(F) \subseteq \text{Attr}_0^1(F) \subseteq \text{Attr}_0^2(F) \subseteq \dots$ and since S is finite, there exists $k \leq |S|$ s.t. $\text{Attr}_0^k(F) = \text{Attr}_0^{k+1}(F)$.

The 0-Attractor is defined as:

$$\text{Attr}_0(F) := \bigcup_{i=0}^{|S|} \text{Attr}_0^i(F)$$

0-Attractor

To show $W_0 = \text{Attr}_0(F)$ and $W_1 = S \setminus \text{Attr}_0(F)$, we construct winning strategies for Player 0 and 1. Define distance from state s to F :

$$d(s, F) := \begin{cases} \min\{i \mid s \in \text{Attr}_0^i(F)\} & \text{if } s \in \text{Attr}_0(F), \\ \infty & \text{otherwise.} \end{cases}$$

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Proof.

$\text{Attr}_0(F) \subseteq W_0$

(a) $\forall s \in S_0 \cap \text{Attr}_0(F) \setminus F \exists s' \in S: (s, s') \in E \wedge d(s', F) < d(s, F)$

(b) $\forall s \in S_1 \cap \text{Attr}_0(F) \setminus F, \forall s' \in S: (s, s') \in E \wedge d(s', F) < d(s, F)$

In $\text{Attr}_0(F) \setminus F$, Player 0 can decrease distance by picking edges according to (a) and Player 1 cannot avoid decreasing the distance because of (b). So, F is reached after a finite number of moves.

0-Attractor cont.

Proof cont.

$$S \setminus \text{Attr}_0(F) \subseteq W_1$$

$$(a) \quad \forall s \in S_0 \cap S \setminus \text{Attr}_0(F) \quad \forall s' \in S: (s, s') \in E \rightarrow s' \notin \text{Attr}_0(F)$$

$$(b) \quad \forall s \in S_1 \cap S \setminus \text{Attr}_0(F), \exists s' \in S: (s, s') \in E \wedge s' \notin \text{Attr}_0(F)$$

In $S \setminus \text{Attr}_0(F)$ Player 1 can choose edges according to (b) leading again to $S \setminus \text{Attr}_0(F)$ and by (a) Player 0 cannot escape from $S \setminus \text{Attr}_0(F)$. So, F will be avoided forever.

$$W_0 = \text{Attr}_0(F) \text{ and } W_1 = S \setminus \text{Attr}_0(F)$$

Safety Games

Given a safety game (G, F) with $G = (S, S_0, E)$, i.e.,

$$\phi_S = \{\rho \in S^\omega \mid \text{Occ}(\rho) \subseteq F\},$$

consider the reachability game $(G, S \setminus F)$, i.e.,

$$\phi_R = \{\rho \in S^\omega \mid \text{Occ}(\rho) \cap (S \setminus F) \neq \emptyset\}.$$

$$\begin{aligned} \text{Then, } S^\omega \setminus \phi_R &= \{\rho \in S^\omega \mid \text{Occ}(\rho) \cap (S \setminus F) = \emptyset\} \\ &= \{\rho \in S^\omega \mid \text{Occ}(\rho) \subseteq F\}. \end{aligned}$$

Player 0 has a safety objective in (G, F) .

Player 1 has a reachability objective in (G, F) .

So, W_0 in the safety game (G, F) corresponds to W_1 in the reachability game $(G, S \setminus F)$.

Homework

Given a reachability game (G, F) with $G = (S, S_0, E)$, find an algorithm that computes the winning regions and strategies in time $O(|E|)$ -time.

Summary

We know how to solve reachability and safety games by positional winning strategies.

The strategies are

- ▶ Player 0: Decrease distance to F
- ▶ Player 1: Stay outside of $\text{Attr}_0(F)$

In LTL, $\diamond F$ = reachability and $\square F$ = safety.

Next, $\square\diamond F$ = Büchi and $\diamond\square F$ = Co-Büchi.

Büchi and Co-Büchi Games

Büchi Game

Given a Büchi game (G, F) over the game graph $G = (S, S_0, E)$ with the set $F \subseteq S$ of **Büchi states**, we aim to

- ▶ determine the winning regions of Player 0 and 1
- ▶ compute their respective winning strategies

Recall, Player 0 wins ρ iff she visits infinitely often states in F , i.e.,
 $\phi = \{\rho \in S^\omega \mid \text{inf}(\rho) \cap F \neq \emptyset\}$.

Idea

Compute for $i \geq 1$ the set Recur_0^i of states $s \in F$ from which Player 0 can force at least i revisits to F .

Then,

$$F \supseteq \text{Recur}_0^1(F) \supseteq \text{Recur}_0^2(F) \supseteq \dots$$

We compute the winning region of Player 0 with

$$\text{Recur}_0(F) := \bigcap_{i \leq 1} \text{Recur}_0^i(F)$$

Again, since F is finite, there exists k such that

$$\text{Recur}_0(F) = \text{Recur}_0^k(F).$$

Claim: $W_0 = \text{Attr}_0(\text{Recur}_0(F))$

One-Step Attractor

We count **revisits**, so we need the set of states from which Player 0 can force a revisit to F , i.e., state from which she can force a visit in ≥ 1 steps.

We define a slightly modified attractor:

$$A_0^0 = \emptyset$$

$$A_0^{i+1} = A_0^i \cup$$

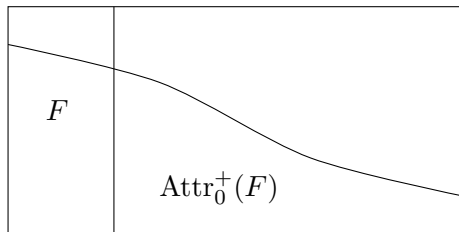
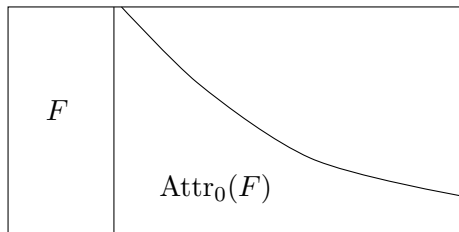
$$\{s \in S_0 \mid \exists s' \in S : (s, s') \in E \wedge s' \in A_0^i \cup F\} \cup$$

$$\{s \in S_1 \mid \forall s' \in S : (s, s') \in E \rightarrow s' \in A_0^i \cup F\}$$

$$\text{Attr}_0^+(F) = \bigcup_{i \geq 0} A_0^i$$

$\text{Attr}_0^+(F)$ is the set of states from which Player 0 can force a revisit to F .

Visit versus Revisit



Recurrence Set

We define

$$\text{Recur}_0^0(F) := F$$

$$\text{Recur}_0^{i+1}(F) := F \cap \text{Attr}_0^+(\text{Recur}_0^i(F))$$

$$\text{Recur}_0(F) := \bigcap_{i \geq 0} \text{Recur}_0^i(F)$$

We show that there exists k such that $\text{Recur}_0(F) := \bigcap_{i \geq 0}^k \text{Recur}_0^i(F)$ by proving $\text{Recur}_0^{i+1}(F) \subseteq \text{Recur}_0^i(F)$ for all $i \geq 0$.

Proof.

▶ $i = 0$: $F \cap \text{Attr}_0^+(F) \subseteq F$

▶ $i \rightarrow i + 1$:

$$\begin{aligned} \text{Recur}_0^{i+2}(F) &= F \cap \text{Attr}_0^+(\text{Recur}_0^{i+1}(F)) \subseteq F \cap \text{Attr}_0^+(\text{Recur}_0^i(F)) \\ &= \text{Recur}_0^{i+1}(F) \end{aligned}$$

Recurrence Set cont.

We show that all states in $\text{Attr}_0(\text{Recur}_0(F))$ are winning for Player 0, i.e., $\text{Attr}_0(\text{Recur}_0(F)) \subseteq W_0$. We construct a memoryless winning strategy for Player 0 for all states in $\text{Attr}_0(\text{Recur}_0(F))$.

Proof.

We know that there exists k such that

$\text{Recur}_0^{k+1}(F) = \text{Recur}_0^k(F) = F \cap \text{Attr}_0^+(\text{Recur}_0^k(F))$. So,

- ▶ for $s \in \text{Recur}_0^k(F) \cap S_0$ Player 0 can choose an edges back to $\text{Attr}_0^+(\text{Recur}_0^k(F))$ and
- ▶ for $s \in \text{Recur}_0^k(F) \cap S_1$ all edges lead back to $\text{Attr}_0^+(\text{Recur}_0^k(F))$.

For all states in $\text{Attr}_0(\text{Recur}_0(F)) \setminus \text{Recur}_0(F)$, Player 0 can follow the attractor strategy to reach $\text{Recur}_0(F)$.



Recurrence Set cont.

We show $S \setminus \text{Attr}_0(\text{Recur}_0(F)) \subseteq W_1$.

Proof.

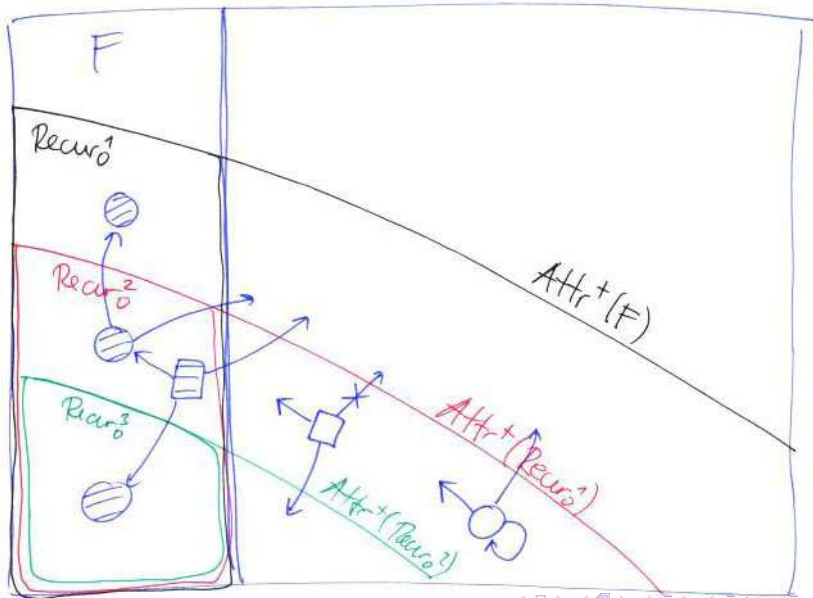
Show: Player 1 can force $\leq i$ visits to F from $s \notin \text{Attr}_0(\text{Recur}_0^i(F))$

$i = 0$: $s \notin \text{Attr}_0(F)$, so Player 1 can avoid visiting F at all.

$i \rightarrow i + 1$: $s \notin \text{Attr}_0(\text{Recur}_0^{i+1}(F))$.

- ▶ $s \notin \text{Attr}_0(\text{Recur}_0^i(F))$, Player 1 plays according to ind. hypothese
- ▶ Otherwise, $s \in \text{Attr}_0(\text{Recur}_0^i(F)) \setminus \text{Attr}_0(\text{Recur}_0^{i+1}(F))$ and Player 1 can avoid $\text{Attr}_0(\text{Recur}_0^{i+1}(F))$. In particular, $s \notin \text{Recur}_0^{i+1}(F) = F \cap \text{Attr}_0^+(\text{Recur}_0^i(F))$.
 - ▶ If $s \in \text{Recur}_0^i$, then Player 1 can force to leave $\text{Attr}_0^+(\text{Recur}_0^i(F))$, otherwise $s \in \text{Recur}_0^{i+1}(F)$. (So, by ind. hyp. at most $i + 1$ visits.)
 - ▶ If $s \in \text{Attr}_0(\text{Recur}_0^i(F)) \setminus \text{Recur}_0^i(F)$, avoid $\text{Attr}_0(\text{Recur}_0^{i+1}(F))$.

Recurrence Set cont.



Büchi games

We have shown that Player 0 has a (memoryless) winning strategy in $\text{Attr}_0(\text{Recur}_0(F))$, so $\text{Attr}_0(\text{Recur}_0(F)) \subseteq W_0$. And, Player 1 has a (memoryless) winning strategy in $S \setminus \text{Attr}_0(\text{Recur}_0(F))$, so $S \setminus \text{Attr}_0(\text{Recur}_0(F)) \subseteq W_1$. This implies the following theorem.

Theorem

Given a Büchi game $((S, S_0, E), F)$, the winning regions W_0 and W_1 are computable and form a partition, i.e., $W_0 \cup W_1 = S$. Both players have memoryless winning strategies.

Co-Büchi Games

Given a Co-Büchi Game $((S, S_0, E), F)$, i.e.,

$$\phi_C = \{\rho \in S^\omega \mid \text{Inf}(\rho) \subseteq F\}$$

consider the Büchi Game $((S, S_0, E), S \setminus F)$, i.e,

$$\phi_B = \{\rho \in S^\omega \mid \text{Inf}(\rho) \cap S \setminus F \neq \emptyset\}.$$

$$\begin{aligned} \text{Then, } S^\omega \setminus \phi_B &= \{\rho \in S^\omega \mid \text{Inf}(\rho) \cap (S \setminus F) = \emptyset\} \\ &= \{\rho \in S^\omega \mid \text{Inf}(\rho) \subseteq F\}. \end{aligned}$$

Player 0 has a co-Büchi objective in (G, F) .

Player 1 has a Büchi objective in (G, F) .

So, W_0 in the co-Büchi game (G, F) corresponds to W_1 in the Büchi game $(G, S \setminus F)$.

Summary

We know how to solve Büchi and Co-Büchi games by positional winning strategies.

In LTL,

- ▶ $\diamond F$ = reachability
- ▶ $\square F$ = safety
- ▶ $\square \diamond F$ = Büchi
- ▶ $\diamond \square F$ = Co-Büchi

Next, Muller and Parity games.