# From Philosophical to Industrial Logic

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## Thread I: Entscheidungsproblem

Entscheidungsproblem (The Decision Problem) [Hilbert-Ackermann, 1928]: Decide if a given first-order sentence is *valid* (dually, *Satisfiable*).

**Church-Turing Theorem**, 1936: The Decision Problem is unsolvable.

Classification Project: Identify decidable fragments of first-order logic.

- Monadic Class
- Bernays-Schönfinkel Class
- Ackermann Class
- Gödel Class (w/o =)

## **Monadic Logic**

**Monadic Class**: First-order logic with = and monadic predicates – captures *syllogisms*.

•  $(\forall x)P(x), (\forall x)(P(x) \to Q(x)) \models (\forall x)Q(x)$ 

[Löwenheim, 1915]: The Monadic Class is decidable.

- *Proof*: Bounded-model property if a sentence is satisfiable, it is satisfiable in a structure of bounded size.
- Proof technique: quantifier elimination.

**Monadic Second-Order Logic**: Allow second-order quantification on monadic predicates.

[Skolem, 1919]: Monadic Second-Order Logic is decidable – via bounded-model property and quantifier elimination.

**Question**: What about <?

## **Thread II: Logic and Automata**

#### Two paradigms in logic:

- Paradigm I: Logic declarative formalism
  - Specify properties of mathematical objects, e.g.,  $(\forall x,y,z)(mult(x,y,z)\leftrightarrow mult(y,x,z))$  commutativity.
- Paradigm II: Machines imperative formalism
  - Specify computations, e.g., Turing machines, finite-state machines, etc.

Surprising Phenomenon: Intimate connection between logic and machines

### **Nondeterministic Finite Automata**

$$A = (\Sigma, S, S_0, \rho, F)$$

- Alphabet. ∑
- States: S
- Initial states:  $S_0 \subseteq S$
- Nondeterministic transition function:

$$\rho: S \times \Sigma \to 2^S$$

• Accepting states:  $F \subseteq S$ 

Input word:  $a_0, a_1, ..., a_{n-1}$ 

Run:  $s_0, s_1, ..., s_n$ 

- $s_0 \in S_0$
- $s_{i+1} \in \rho(s_i, a_i)$  for  $i \ge 0$

**Acceptance**:  $s_n \in F$ 

**Recognition**: L(A) – words accepted by A.

Example:  $\longrightarrow \bullet \xrightarrow{1} \bullet - \text{ends with 1's}$ 

**Fact**: NFAs define the class *Reg* of regular languages.

## **Logic of Finite Words**

View finite word  $w = a_0, \dots, a_{n-1}$  over alphabet  $\Sigma$  as a mathematical structure:

- Domain: 0, ..., n-1
- Binary relation: <</li>
- Unary relations:  $\{P_a : a \in \Sigma\}$

#### First-Order Logic (FO):

- Unary atomic formulas:  $P_a(x)$  ( $a \in \Sigma$ )
- Binary atomic formulas: x < y

**Example**:  $(\exists x)((\forall y)(\neg(x < y)) \land P_a(x))$  – last letter is a.

### Monadic Second-Order Logic (MSO):

- Monadic second-order quantifier:  $\exists Q$
- New unary atomic formulas: Q(x)

#### NFA vs. MSO

**Theorem** [Büchi, Elgot, Trakhtenbrot, 1957-8 (independently)]: MSO = NFA

Both MSO and NFA define the class Reg.

**Proof**: Effective

- From NFA to MSO  $(A \mapsto \varphi_A)$ 
  - Existence of run existential monadic quantification
  - Proper transitions and acceptance first-order formula
- From MSO to NFA  $(\varphi \mapsto A_{\varphi})$ : closure of NFAs under
  - Union disjunction
  - Projection existential quantification
  - Complementation negation

## **NFA Complementation**

#### Run Forest of A on w:

- Roots: elements of  $S_0$ .
- Children of s at level i: elements of  $\rho(s, a_i)$ .
- Rejection: no leaf is accepting.

**Key Observation**: collapse forest into a DAG – at most one copy of a state at a level; width of DAG is |S|.

## Subset Construction Rabin-Scott, 1959:

- $A^c = (\Sigma, 2^S, \{S_0\}, \rho^c, F^c)$   $F^c = \{T : T \cap F = \emptyset\}$   $\rho^c(T, a) = \bigcup_{t \in T} \rho(t, a)$   $L(A^c) = \Sigma^* L(A)$

## **Complementation Blow-Up**

$$A = (\Sigma, S, S_0, \rho, F), |S| = n$$
  
 $A^c = (\Sigma, 2^S, \{S_0\}, \rho^c, F^c)$ 

**Blow-Up**:  $2^n$  upper bound

Can we do better?

Lower Bound:  $2^n$ 

Sakoda-Sipser 1978, Birget 1993

$$\begin{split} L_n &= (0+1)^* 1 (0+1)^{n-1} 0 (0+1)^* \\ \bullet & \ \underline{L_n} \text{ is easy for NFA} \\ \bullet & \ \overline{L_n} \text{ is hard for NFA} \end{split}$$

## **NFA Nonemptiness**

Nonemptiness:  $L(A) \neq \emptyset$ 

Nonemptiness Problem: Decide if given A is nonempty.

Directed Graph  $G_A = (S, E)$  of NFA A = $(\Sigma, S, S_0, \rho, F)$ :
• Nodes: S

- Edges:  $E = \{(s,t) : t \in \rho(s,a) \text{ for some } a \in A \in A \}$

**Lemma**: A is nonempty iff there is a path in  $G_A$  from  $S_0$  to F.

 Decidable in time linear in size of A, using breadth-first search or depth-first search.

## **MSO Satisfiability – Finite Words**

Satisfiability:  $models(\psi) \neq \emptyset$ 

Satisfiability Problem: Decide if given  $\psi$  is satisfiable.

**Lemma**:  $\psi$  is satisfiable iff  $A_{\psi}$  is nonnempty.

**Corollary**: MSO satisfiability is decidable.

- Translate  $\psi$  to  $A_{\psi}$ .
- Check nonemptiness of  $A_{\psi}$ .

## Complexity:

Upper Bound: Nonelementary Growth

$$2^{\cdot \cdot^{2^n}}$$

(tower of height O(n))

• Lower Bound [Stockmeyer, 1974]: Satisfiability of FO over finite words is nonelementary (no bounded-height tower).

## **Thread III: Sequential Circuits**

Church, 1957: Use logic to specify sequential circuits.

## **Sequential circuits**: $C = (I, O, R, f, g, R_0)$

- *I*: input signals
- O: output signals
- R: sequential elements
- $f: 2^I \times 2^R \to 2^R$ : transition function  $g: 2^R \to 2^O$ : output function
- $R_0 \in 2^R$ : initial assignment

Trace: element of  $(2^I \times 2^R \times 2^O)^\omega$ 

$$t = (I_0, R_0, O_0), (I_1, R_1, O_1), \dots$$

- $\bullet \ R_{j+1} = f(I_j, R_j)$
- $\bullet$   $O_i = g(R_i)$

## **Specifying Traces**

View infinite trace  $t = (I_0, R_0, O_0), (I_1, R_1, O_1), \ldots$  as a mathematical structure:

- Domain: N
- Binary relation: <</li>
- Unary relations:  $I \cup R \cup O$

#### First-Order Logic (FO):

- Unary atomic formulas: P(x) ( $P \in I \cup R \cup O$ )
- Binary atomic formulas: x < y

**Example**:  $(\forall x)(\exists y)(x < y \land P(y)) - P$  holds i.o.

## Monadic Second-Order Logic (MSO):

- Monadic second-order quantifier:  $\exists Q$
- New unary atomic formulas: Q(x)

**Model-Checking Problem**: Given circuit C and formula  $\varphi$ ; does  $\varphi$  hold in all traces of C?

**Easy Observation**: Model-checking problem reducible to satisfiability problem — use FO to encode the "logic" (i.e., f, g) of the circuit C.

### Büchi Automata

## Büchi Automaton: $A = (\Sigma, S, S_0, \rho, F)$

- Alphabet:  $\Sigma$

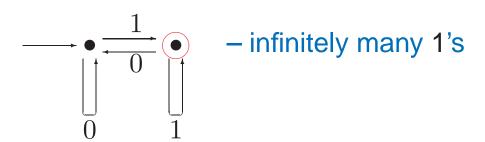
- States: S• Initial states:  $S_0 \subseteq S$  Transition function:  $\rho: S \times \Sigma \to 2^S$
- Accepting states:  $F \subseteq S$

Input word:  $a_0, a_1, \ldots$ 

**Run**:  $s_0, s_1, ...$ 

- $s_0 \in S_0$
- $s_{i+1} \in \rho(s_i, a_i) \text{ for } i \ge 0$

**Acceptance**: F visited infinitely often



**Fact**: Büchi automata define the class  $\omega$ -Reg of  $\omega$ regular languages.

## Logic vs. Automata II

Paradigm: Compile high-level logical specifications into low-level finite-state language

**Compilation Theorem**: [Büchi,1960] Given an MSO formula  $\varphi$ , one can construct a Büchi automaton  $A_{\varphi}$  such that a trace  $\sigma$  satisfies  $\varphi$  if and only if  $\sigma$  is accepted by  $A_{\varphi}$ .

### **MSO Satisfiability Algorithm:**

- 1.  $\varphi$  is satisfiable iff  $L(A_{\varphi}) \neq \emptyset$
- 2.  $L(\Sigma, S, S_0, \rho, F) \neq \emptyset$  iff there is a path from  $S_0$  to a state  $f \in F$  and a cycle from f to itself.

**Corollary** [Church, 1960]: Model checking sequential circuits wrt MSO specs is decidable.

Church, 1960: "Algorithm not very efficient" (nonelementary complexity, [Stockmeyer, 1974]).

## **Catching Bugs with A Lasso**

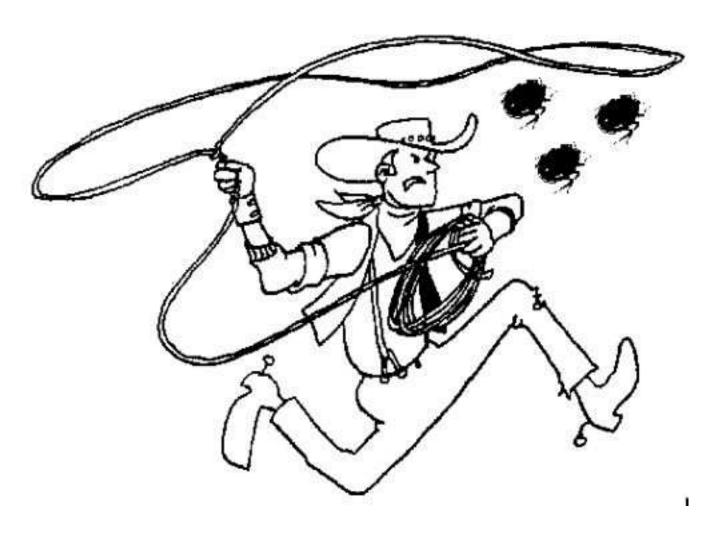
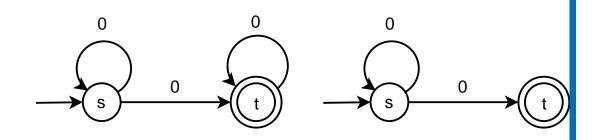


Figure 1: Ashutosh's Blog, November 23, 2005

## **Büchi Complementation**

**Problem:** subset construction fails!



$$\rho(\{s\},0) = \{s,t\}, \, \rho(\{s,t\},0) = \{s,t\}$$

### **History**

Büchi'62: doubly exponential construction.

• SVW'85:  $16^{n^2}$  upper bound

• Safra'88:  $n^{2n}$  upper bound

• Michel'88:  $(n/e)^n$  lower bound

• KV'97:  $(6n)^n$  upper bound

• FKV'04:  $(0.97n)^n$  upper bound

• Yan'06:  $(0.76n)^n$  lower bound

• Schewe'09:  $(0.76n)^n$  upper bound

## **Thread IV: Temporal Logic**

Prior, 1914–1969, Philosophical Preoccupations:

- Religion: Methodist, Presbytarian, atheist, agnostic
- Ethics: "Logic and The Basis of Ethics", 1949
- Free Will, Predestination, and Foreknowledge:
- "The future is to some extent, even if it is only a very small extent, something we can make for ourselves".
- "Of what will be, it has now been the case that it will be."
- "There is a deity who infallibly knows the entire future."

Mary Prior: "I remember his waking me one night [in 1953], coming and sitting on my bed, ..., and saying he thought one could make a formalised tense logic."

1957: "Time and Modality"

## Linear vs. Branching Time, A

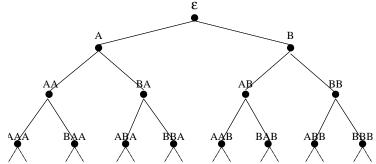
- Prior's first lecture on tense logic, Wellington University, 1954: linear time.
- Prior's "Time and modality", 1957: relationship between linear tense logic and modal logic.
- Sep. 1958, letter from Saul Kripke: "[I]n an indetermined system, we perhaps should not regard time as a linear series, as you have done. Given the present moment, there are several possibilities for what the next moment may be like and for each possible next moment, there are several possibilities for the moment after that. Thus the situation takes the form, not of a linear sequence, but of a 'tree'". (Kripke was a high-school student, not quite 18, in Omaha, Nebraska.)

## Linear vs. Branching Time, B

- Linear time: a system induces a set of traces
- Specs: describe traces

...

- Branching time: a system induces a trace tree
- Specs: describe trace trees



## Linear vs. Branching Time, C

 Prior developed the idea into Ockhamist and Peircean theories of branching time (branching-time logic without path quantifiers)

Sample formula: CKMpMqAMKpMqMKqMp

• Burgess, 1978: "Prior would agree that the determinist sees time as a line and the indeterminist sees times as a system of forking paths."

## Linear vs. Branching Time, D

#### **Philosophical Conundrum**

- Prior:
- Nature of course of time branching
- Nature of course of events linear
- Rescher:
- Nature of time linear
- Nature of course of events branching
- "We have 'branching in time', not 'branching of time".

Linear time: Hans Kamp, Dana Scott and others continued the development of linear time during the 1960s.

## **Temporal and Classical Logics**

### **Key Theorem:**

• Kamp, 1968: Linear temporal logic with past and binary temporal connectives ("until" and "since") has precisely the expressive power of FO over the integers.

## The Temporal Logic of Programs

#### Precursors:

- Prior: "There are practical gains to be had from this study too, for example in the representation of time-delay in computer circuits"
- Rescher & Urquhart, 1971: applications to processes ("a programmed sequence of states, deterministic or stochastic")

## "Big Bang 1" [Pnueli, 1977]:

- Future linear temporal logic (LTL) as a logic for the specification of non-terminating programs
- Temporal logic with "eventually" and "always" (later, with "next" and "until")
- Model checking via reduction to MSO and automata

**Crux**: Need to specify ongoing behavior rather than input/output relation!

## **Linear Temporal Logic**

Linear Temporal logic (LTL): logic of temporal sequences (Pnueli, 1977)

### Main feature: time is implicit

- $next \varphi$ :  $\varphi$  holds in the next state.
- eventually  $\varphi$ :  $\varphi$  holds eventually
- always  $\varphi$ :  $\varphi$  holds from now on
- $\varphi$  until  $\psi$ :  $\varphi$  holds until  $\psi$  holds.

• 
$$\pi, w \models next \varphi \text{ if } w \bullet \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \bullet \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \bullet \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \bullet \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \underline{\hspace{1cm}} \bullet \underline{\hspace{1cm}} \underline{\hspace{1cm}$$

• 
$$\pi, w \models \varphi \ until \ \psi \ \text{if} \ w \bullet \longrightarrow \varphi \qquad \varphi \qquad \psi \longrightarrow \cdots$$

## **Examples**

- always not (CS<sub>1</sub> and CS<sub>2</sub>): mutual exclusion (safety)
- always (Request implies eventually Grant):
   liveness
- always (Request implies (Request until Grant)): liveness

## **Expressive Power**

- Gabbay, Pnueli, Shelah & Stavi, 1980: Propositional LTL has precisely the expressive power of FO over the naturals.
- Thomas, 1979: FO over naturals has the expressive power of star-free  $\omega$ -regular expressions

**Summary**: LTL=FO=star-free  $\omega$ -RE < MSO= $\omega$ -RE

Meyer on LTL, 1980, in "Ten Thousand and One Logics of Programming":

"The corollary due to Meyer – I have to get in my controversial remark – is that that [GPSS'80] makes it theoretically uninteresting."

## **Computational Complexity**

**Recall**: Satisfiability of FO over traces is nonelementary

#### **Contrast with LTL:**

- Wolper, 1981: LTL satisfiability is in EXPTIME.
- Halpern&Reif, 1981, Sistla&Clarke, 1982:
   LTL satisfiability is PSPACE-complete.

**Basic Technique**: *tableau* (influenced by branching-time techniques)

## **Model Checking**

"Big Bang 2" [Clarke & Emerson, 1981, Queille & Sifakis, 1982]: Model checking programs of size m wrt CTL formulas of size n can be done in time mn.

**Linear-Time Response** [Lichtenstein & Pnueli, 1985]: Model checking programs of size m wrt LTL formulas of size n can be done in time  $m2^{O(n)}$  (*tableau*-based).

## Seemingly:

Automata: Nonelementary

Tableaux: exponential

#### **Back to Automata**

#### **Exponential-Compilation Theorem:**

[V. & Wolper, 1983-1986]

Given an LTL formula  $\varphi$  of size n, one can construct a Büchi automaton  $A_{\varphi}$  of size  $2^{O(n)}$  such that a trace  $\sigma$  satisfies  $\varphi$  if and only if  $\sigma$  is accepted by  $A_{\varphi}$ .

#### **Automata-Theoretic Algorithms:**

1. LTL Satisfiability:

 $\varphi$  is satisfiable iff  $L(A_{\varphi}) \neq \emptyset$  (PSPACE)

2. LTL Model Checking:

$$M \models \varphi \text{ iff } L(M \times A_{\neg \varphi}) = \emptyset \text{ (}m2^{O(n)}\text{)}$$

#### **Reduction to Practice**

#### **Practical Theory:**

- Courcoubetis, V., Yannakakis & Wolper, 1989:
   Optimized search algorithm for explicit model checking
- Burch, Clarke, McMillan, Dill & Hwang, 1990:
   Symbolic algorithm for LTL compilation
- Clarke, Grumberg & Hamaguchi, 1994: Optimized symbolic algorithm for LTL compilation
- Gerth, Peled, V. & Wolper, 1995: Optimized explicit algorithm for LTL compilation

#### Implementation:

- COSPAN [Kurshan, 1983]: deterministic automata specs
- Spin [Holzmann, 1995]: Promela w. LTL:
- SMV [McMillan, 1995]: SMV w. LTL

Satisfactory solution to Church's problem? Almost, but not quite, since LTL<MSO= $\omega$ -RE.

## **Enhancing Expressiveness**

- Wolper, 1981: Enhance LTL with grammar operators, retaining EXPTIME-ness (PSPACE [SC'82])
- V. & Wolper, 1983: Enhance LTL with automata, retaining PSPACE-completeness
- Sistla, V. & Wolper, 1985: Enhance LTL with 2ndorder quantification, losing elementariness
- V., 1989: Enhance LTL with fixpoints, retaining PSPACE-completeness

**Bottom Line**: ETL (LTL w. automata) =  $\mu$ TL (LTL w. fixpoints) = MSO, and has exponential-compilation property.

## Thread V: Dynamic and Branching-Time Logics

#### **Dynamic Logic** [Pratt, 1976]:

- The  $\Box \varphi$  of modal logic can be taken to mean " $\varphi$  holds after an execution of a program step".
- Dynamic modalities:
- $[\alpha]\varphi \varphi$  holds after all executions of  $\alpha$ .
- $\psi \to [\alpha] \varphi$  corresponds to Hoare triple  $\{\psi\} \alpha \{\varphi\}$ .

**Propositional Dynamic Logic** [Fischer & Ladner, 1977]: *Boolean* propositions, programs – *regular expressions* over *atomic* programs.

**Satisfiability** [Pratt, 1978]: EXPTIME – using *tableau*-based algorithm

Extensions to nonterminating programs [Streett 1981, Harel & Sherman 1981] – awkward compared to linear temporal logic.

## **Branching-Time Logic**

From dynamic logic back to temporal logic: The dynamic-logic view is clearly branching; what is the analog for temporal logic?

- Emerson & Clarke, 1980: correcteness properties as fixpoints over computation trees
- Ben-Ari, Manna & Pnueli, 1981: branching-time logic UB; saistisfiability in EXPTIME using tablueax
- Clarke & Emerson, 1981: branching-time logic
   CTL; efficient model checking
- Emerson & Halpern, 1983: branching-time logic
   CTL\* ultimate branching-time logic

### Key Idea: Prior missed path quantifiers

ullet  $\forall \ eventually \ p$ : on all possible futures, p eventually happen.

## **Linear vs. Branching Temporal Logics**

- Linear time: a system generates a set of computations
- Specs: describe computations
- LTL: always(request  $\rightarrow eventually$  grant)

- Branching time: a system generates a computation tree
- Specs: describe computation trees
- CTL:  $\forall always$  (request  $\rightarrow \forall eventually$  grant)

## Combining Dynamic and Temporal Logics

### Two distinct perspectives:

- Temporal logic: state based
- Dynamic logic: action based

### Symbiosis:

- Harel, Kozen & Parikh, 1980: Process Logic (branching time)
- V. & Wolper, 1983: Yet Another Process Logic (branching time)
- Harel and Peleg, 1985: Regular Process Logic (linear time)
- Henriksen and Thiagarajan, 1997: Dynamic LTL (linear time)

#### **Tech Transfer:**

- Beer, Ben-David & Landver, IBM, 1998:
   RCTL (branching time)
- Beer, Ben-David, Eisner, Fisman, Gringauze, Rodeh, IBM, 2001: Sugar (branching time)

#### Thread VI: From LTL to PSL

#### **Model Checking at Intel**

### Prehistory:

- 1990: successful feasibility study using Kurshan's COSPAN
- 1992: a pilot project using CMU's SMV
- 1995: an internally developed (linear time) property-specification language

#### History:

- 1997: Development of 2nd-generation technology started (engine and language)
- 1999: BDD-based model checker released
- 2000: SAT-based model checker released
- 2000: ForSpec (language) released

#### Dr. Vardi Goes to Intel

1997: (w. Fix, Hadash, Kesten, & Sananes)

V.: How about LTL?

F., H., K., & S.: Not expressive enough.

V.: How about ETL?  $\mu$ TL?

F., H., K., & S.: Users will object.

1998 (w. Landver)

V.: How about ETL?

L.: Users will object.

L.: How about regular expressions?

V.: They are equivalent to automata!

**RELTL**: LTL plus dynamic modalities, interpreted linearly –  $[e]\varphi$ 

**Easy**: RELTL=ETL= $\omega$ -RE

ForSpec: RELTL + hardware features (clocks and resets) [Armoni, Fix, Flaisher, Gerth, Ginsburg, Kanza, Landver, Mador-Haim, Singerman, Tiemeyer, V., Zbar]

## From ForSpec to PSL

#### Industrial Standardization:

- Process started in 2000
- Four candidates: IBM's Sugar, Intel's ForSpec, Mororola's CBV, and Verisity's E.
- Fierce debate on linear vs. branching time

#### Outcome:

- Big political win for IBM (see references to PSL/Sugar)
- Big technical win for Intel
- PSL is LTL + RE + clocks + resets
- Branching-time extension as an acknowledgement to Sugar
- Some evolution over time in hardware features
- Major influence on the design of SVA (another industrial standard)

Bottom Line: Huge push for model checking in industry.

## **Some Philosophical Points**

- Science is a cathedral; we are the masons.
- There is no architect; outcome is unpredictable.
- Most of our contributions are smaller than we'd like to think.
- Even small contributions can have major impact.
- Much is forgotten and has to be rediscovered.